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# Matrices, Systems, Determinants

Let's start off by defining a few terms

Linear independence: ~~Our vectors, equations, rows all the same~~

There is no scalar combination of the vectors that sums to  $\vec{0}$

Equations, rows

Rank: The rank of a matrix is the maximum number of linearly independent row vectors

How do I find it: Gaussian Elimination

Over-determined System: More equations than unknowns

Under-determined System: More unknowns than equations

Solutions to Linear Systems:

Given the following system of equations:

$$\begin{aligned} 3x + 2y + z &= 4 \\ 6x + y + 2z &= 6 \end{aligned}$$

Find a solution:

① Set up in Augmented Matrix Form

$$\underbrace{\left[ \begin{array}{ccc|c} 3 & 2 & 1 & 4 \\ 6 & 1 & 2 & 6 \end{array} \right]}_{\text{Coefficients Matrix}} \quad \underbrace{\left[ \begin{array}{c} \\ \end{array} \right]}_{\text{Solution vector}}$$

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② Perform Gauss elimination until 1 coefficient matrix is in upper triangular form

→ pivots

$$\left[ \begin{array}{cc|cc} 3 & 2 & 1 & 4 \\ 6 & 1 & 2 & 6 \end{array} \right]$$

upper  $\Delta$  form:

$$\left[ \begin{array}{cccc} a_{11} & a_{12} & \cdots & a_{1n} \\ 0 & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & a_{nn} \end{array} \right]$$

a. 1st Operation:

$$\left[ \begin{array}{cc|cc} 3 & 2 & 1 & 4 \\ 6 & 1 & 2 & 6 \end{array} \right] \xrightarrow{2R_1 - R_2 = R_2} \text{all zeros below diagonal}$$

$$= \left[ \begin{array}{cc|cc} 3 & 2 & 1 & 4 \\ 0 & 3 & 0 & 2 \end{array} \right] \text{Do we go any further? No}$$

b. Solve for  $y$ :

$$y = 2/3$$

Solve for  $x$

$$x = 4 - \frac{1}{3} - z \stackrel{=?}{=} ?$$

Can we find  $z$ ?  
The system is under-determined

③ Find a solution:

let

$$\boxed{\begin{aligned} z &= 0 \\ y &= 2/3 \\ x &= 4 - \frac{1}{3} - 0 = 8/3 \end{aligned}}$$

## Determinants

→ needed  
for Eigen value/vector  
problems! (3)

Determinants were originally introduced for solving linear systems (from book)  
↓ Bad idea, computationally expensive

but they have important engineering applications in Eigen values problems!

$$\text{Let } D = \det A = \begin{vmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{n1} & \cdots & a_{nn} \end{vmatrix} \rightarrow A \text{ must be square!}$$

↑ straight brackets represent det

how do we find  $D$ ?

Let's start w/a  $2 \times 2$ :

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

$$D = \det A = \begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc$$

Once we can find the det of a  $2 \times 2$ , we can find it for any size matrix

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Ex: Find  $\begin{vmatrix} 2 & 1 \\ 1 & 2 \end{vmatrix} = 2 \cdot 2 - 1 \cdot 1 = 3$

Now lets look at a  $3 \times 3$

Ex: Find  $\begin{vmatrix} 3 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 2 & 2 \end{vmatrix}$

How?

we will do this through coFactor expansion

- ① choose any row or column.

I chose row 1

$$\begin{vmatrix} 3 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 2 & 2 \end{vmatrix}$$

- ② Next select the first element in your chosen row or column

$$\begin{vmatrix} 3 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 2 & 2 \end{vmatrix}$$

and now pull out the submatrix that does not correspond to the row & column the chosen element is in.

$$\begin{bmatrix} 1 & 1 \\ 2 & 2 \end{bmatrix}$$

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- (3) Multiply the determinant of the submatrix by ~~you~~ the chosen element:

$$3 \begin{vmatrix} 1 & 1 \\ 2 & 2 \end{vmatrix} = 3(1 \cdot 2 - 2 \cdot 1) = 0$$

- (4) Assign a sign (+ or -) based on the location of the element:

Method 1:

for a  $3 \times 3$ 

$$\begin{bmatrix} + & - & + \\ - & + & - \\ + & - & + \end{bmatrix}$$

Method 2:

$$(-1)^{j+k}$$

where  $j$  is the row of the element &  $k$  is the column

$$(-1)^{1+1} = 1 = +$$

- (5) repeat process for every element in chosen row:

$$\begin{vmatrix} 3 & 1 & + \\ 0 & 1 & 1 \\ 0 & 2 & 2 \end{vmatrix}$$

$$1 \cdot \begin{vmatrix} 0 & 1 \\ 0 & 2 \end{vmatrix} = 0$$

$$\text{sign } (-1)^{1+2} = -$$

$$\begin{vmatrix} 3 & + & 1 \\ 0 & 1 & 1 \\ 0 & 2 & 2 \end{vmatrix}$$

$$1 \cdot \begin{vmatrix} 0 & 1 \\ 0 & 2 \end{vmatrix} = 0$$

$$\text{sign } (-1)^{1+3} = +$$

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(6) Sum up the pieces:

$$+0 -0 +0 = 0$$

Second Example:

Find:

$$\begin{vmatrix} 2 & 1 & 1 \\ 0 & 1 & 0 \\ 3 & 1 & 1 \end{vmatrix}$$

? does it matter which row or column I choose? NO

(1) What's a good choice for our row or column?

$$\begin{vmatrix} 2 & | & 1 \\ 0 & | & 0 \\ 3 & | & 1 \end{vmatrix}$$

two zeros, so all I need to look at is the middle piece.

$$(-1)^{2+2} \cdot 1 \cdot \begin{vmatrix} 2 & 1 \\ 3 & 1 \end{vmatrix} = 1 \cdot (2-3) = \underline{\underline{-1}}$$

Easy when there are a lot of zeros.

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one last Example:

$$\left| \begin{array}{cccc} 1 & 2 & 3 & 4 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 1 \end{array} \right|$$

(1) we choose a row & expand

$$\left| \begin{array}{cccc} 1 & 2 & 3 & 4 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 1 \end{array} \right|$$

$\circlearrowleft \quad a_{4,4}$

$$(-1)^{4+4} \cdot 1 \cdot \left| \begin{array}{ccc} 1 & 2 & 3 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{array} \right|$$

This is a  $3 \times 3$ ,  
so we have  
to expand  
again on this  
smaller matrix.

$$\left| \begin{array}{ccc} 1 & 2 & 3 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{array} \right|$$

$$(-1)^{3+3} \cdot 1 \cdot \left| \begin{array}{cc} 1 & 2 \\ 0 & 1 \end{array} \right|$$

$$= 1 \cdot (1 \cdot 1 - 0) \\ = 1$$

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$$(-1)^{4+4} \cdot 1 \cdot 1 = 1$$

or if we follow the math & realize all signs are positive, we get

$$1 \cdot 1 \cdot 1 \cdot 1 = 1$$

Now For Bonus Find :

$$\begin{vmatrix} 5 & 4 & 3 & 2 & 1 \\ 0 & 4 & 3 & 2 & 1 \\ 0 & 0 & 3 & 2 & 1 \\ 0 & 0 & 0 & 2 & 1 \\ 0 & 0 & 0 & 0 & 1 \end{vmatrix}$$

hint, look  
at the  
above example

Show me the work in your exam!

Cramers Rule:

A terrible way to solve a linear system of equations : (numerically unstable!)

Given :  $a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1$

$$\underbrace{\begin{array}{l} \vdots \\ a_{n1}x_1 + a_{n2}x_2 + \dots + a_{nn}x_n = b_n \end{array}}_{\text{System of equations}}$$

$$Ax = \vec{b}$$

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$$x_1 = \frac{D_1}{D}, x_2 = \frac{D_2}{D}, x_3 = \frac{D_3}{D}, \dots x_n = \frac{D_n}{D}$$

where  $D = \det(A)$

&  $D_1$  is the

$$\det \left( \begin{array}{cccc} b_1 & a_{12} & \cdots & a_{1n} \\ \vdots & \vdots & & \vdots \\ \vdots & \vdots & & \vdots \\ b_n & a_{n2} & \cdots & a_{nn} \end{array} \right)$$

&  $D_2$  is the

$$\det \left( \begin{array}{ccccc} a_{11} & b_1 & a_{13} & \cdots & a_{1n} \\ \vdots & \vdots & \vdots & & \vdots \\ \vdots & \vdots & \vdots & & \vdots \\ a_{n1} & b_n & a_{n3} & \cdots & a_{nn} \end{array} \right)$$

etc:

Example: Solve

$$\begin{aligned} 3x + 4y &= 3 \\ 2x + 5y &= 1 \end{aligned}$$

$$D = \begin{vmatrix} 3 & 4 \\ 2 & 5 \end{vmatrix} = 3 \cdot 5 - 2 \cdot 4 = 7$$

$$x_1 = \frac{11}{7}$$

$$D_1 = \begin{vmatrix} 3 & 4 \\ 1 & 5 \end{vmatrix} = 3 \cdot 5 - 4 \cdot 1 = 11$$

$$x_2 = \frac{-3}{7}$$

$$D_2 = \begin{vmatrix} 3 & 3 \\ 2 & 1 \end{vmatrix} = 3 \cdot 1 - 2 \cdot 3 = -3$$

⑩

## Inverse of A matrix

The inverse can be used to solve a linear system of equations as follows:

$$\text{Given: } A\vec{x} = \vec{b}$$

$$\text{then: } \vec{x} = A^{-1}\vec{b}$$

This is a computationally expensive & numerically unstable technique.

What is  $A^{-1}$ ?

$A^{-1}$  is the matrix that when multiplied by  $A$ , gives the Identity matrix:

$$A^{-1}A = I = AA^{-1}$$

$$B^{-1}B = I = BB^{-1}$$

An inverse exists if the rank of  $A$  is  $n$ , thus, if & only if  $\det(A) \neq 0$

Find

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## Finding an Inverse:

Given  $A = \begin{bmatrix} 2 & 1 \\ 1 & 3 \end{bmatrix}$ , find  $A^{-1}$

- Create an augmented Matrix:

$$\begin{bmatrix} A & | & I \end{bmatrix} = \begin{bmatrix} (2) & (1) & | & (1) & (0) \\ (1) & (3) & | & (0) & (1) \end{bmatrix}$$

- Perform row operations until  $A$  is an Identity matrix:

$$\begin{bmatrix} 2 & 1 & | & 1 & 0 \\ 1 & 3 & | & 0 & 1 \end{bmatrix} R_1 - 2R_2 = R_2$$

$$\begin{bmatrix} 2 & 1 & | & 1 & 0 \\ 0 & -5 & | & 1 & -2 \end{bmatrix} R_2 = R_2 / -5$$

$$\begin{bmatrix} 2 & 1 & | & 1 & 0 \\ 0 & 1 & | & -\frac{1}{5} & \frac{2}{5} \end{bmatrix} R_1 = R_1 - R_2$$

$$\begin{bmatrix} 2 & 0 & | & \frac{6}{5} & -\frac{3}{5} \\ 0 & 1 & | & -\frac{1}{5} & \frac{2}{5} \end{bmatrix} R_1 = R_1 / 2$$

$$\begin{bmatrix} 1 & 0 & | & \frac{6}{10} & -\frac{3}{10} \\ 0 & 1 & | & -\frac{1}{10} & \frac{2}{10} \end{bmatrix}$$

- The inverse is now where the Id Matrix was:

$$A^{-1} = \begin{bmatrix} \frac{6}{10} & -\frac{3}{10} \\ -\frac{1}{10} & \frac{2}{10} \end{bmatrix}$$