

## MA205 Graded Homework Due 14 November

Instructions:

**For questions (1-3), do the following:**

- State the Differential Equation.
- Solve the Differential Equation for  $x(t)$  IOT find the Particular Solution.

\*\*Note: Calculations must be done by hand-show all work. Confirm calculations by using Mathematica DSolve command. Turn-in both calculations done by hand and Mathematica work.

- Plot the particular solution in Mathematica. Comment on the long-term behavior of the function.
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### Question 1-Spring Mass System No-Damping

A spring with a 7-kg mass is held stretched 1.4 m beyond its natural length by a force of 80 N. If the spring begins at its equilibrium position but a push gives it an initial velocity of 1.2 m/s. What is the position when  $t=5$  seconds.

### Question 2-Spring Mass System Damping

A spring with a mass of 2 kg has damping constant 14, and a force of 6 N is required to keep the spring stretched 0.5 m beyond its natural length. The spring is stretched 1m beyond its natural length and then released with zero velocity. What is the position when  $t=5$  seconds.

### Question 3-Spring Mass System Damping

A mass weighing 32lbs stretches a spring 8 feet beyond its natural length. The mass is released with an upward velocity of -0.5 ft/sec, from a position 2 feet below its equilibrium position. The subsequent motion of the mass takes place in a medium that offers a damping force of .5 times the instantaneous velocity.

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### Question 4

Two tanks each containing 50 gallons of salt solution. Initially tank A contains 10 lbs of Salt, and tank B contains 20 lbs of Salt. A solution containing 3 lbs of salt per gallon enters tank A at the rate of 2 gallon per minute and the well-stirred mixture drains from tank A to tank B at the same rate. The mixture in tank B is kept well-stirred and is drained off at the rate of 2 gallons per minute. **Setup the differential equations and put in matrix form.**

$$m = 7 \text{ kg}$$

No damping

$$X = 1.4$$

$$mx'' + kx = 0$$

$$F = kX$$

$$7x'' + 57.14x = 0$$

$$80N = 1.4k$$

$$7r^2 + 57.14 = 0$$

$$57.14 = k$$

$$r^2 + 8.1 = 0$$

$$x(0) = 0$$

$$\omega = 0$$

$$x'(0) = 1.2 \frac{\text{m}}{\text{s}}$$

$$r = \pm \sqrt{8.1} \text{ rad/s} \quad \text{so} \quad \beta = 8$$

Case III no damping vert.

general solution

$$\text{Case III} \quad y = e^{-\alpha t} (c_1 \cos(\beta t) + c_2 \sin(\beta t))$$

No damping

$$\underline{\underline{\alpha = 0}}$$

$$y = e^{0t} (c_1 \cos(8.1t) + c_2 \sin(8.1t))$$

$$y(0) = c_1 = 0$$

$$y'(0) = -\sqrt{8.1} c_1 \sin(0) + \sqrt{8.1} c_2 \cos(0)$$

$$y'(0) = \sqrt{8.1} c_2 = 1.2$$

$$c_2 = .42$$

$$\text{So} \quad y = .42 \sin(8.1t)$$

ANS

$$\text{at } t = 5$$

$$y(5) = .42 \sin(8.1(5)) = \underline{\underline{.41 \text{ ft}}}$$

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$$M = 2 \text{ kg}$$

$$C = 14$$

$$F = Kx \quad \begin{cases} F = 6N \\ x = \text{distance from} \\ \text{strikedown} = r \end{cases}$$

$$6 = .5K \quad \text{strikedown} = r$$

$$12 = K$$

$$mx'' + cx' + kx = 0$$

$$2x'' + 14x' + 12x = 0$$

$$2r^2 + 14r + 12 = 0$$

$$2(r^2 + 7r + 6) = 0$$

$$2(r+1)(r+6) = 0$$

2 Real Roots  $\Rightarrow$ 

$$r = -1, -6$$

Case I  $\rightarrow$  Overdamped

$$x = C_1 e^{rt} + C_2 e^{-6t}$$

$$x = C_1 e^{-t} + C_2 e^{-6t}$$

$$x(0) = 1$$

$$x'(0) = 0$$

$$x(0) = C_1 + C_2 = 1$$

$$x'(t) = -C_1 e^{-t} - 6C_2 e^{-6t}$$

$$x'(0) = -C_1 - 6C_2 = 0$$

$$\begin{aligned} C_1 + C_2 &= 1 \\ -C_1 - 6C_2 &= 0 \end{aligned}$$

$$-5C_2 = 1$$

$$x = \frac{6}{5}e^{-t} - \frac{1}{5}e^{-6t}$$

ANS

$$C_1 = \frac{1}{5} \quad x(5) = \frac{6}{5} - .008$$

$$C_1 = \frac{1}{5}$$

$$Q3 \quad x = 84$$

$$F = 32 \text{ lbs}$$

Spry of damping

$$F = kx$$

$$mx'' + dx' + kx = 0$$

$$32 = kx$$

$$x'' + .5x' + 4x = 0$$

$$k = 4$$

$$r^2 + \frac{1}{2}r + 4 = 0$$

$$mg = F, m = \frac{F}{g}, g = \frac{32 \text{ ft}}{\text{sec}^2}$$

$$r = -2.5 \pm 1.98i$$

$$32 = m$$

$$\alpha \pm Bi$$

$$\frac{32}{32}$$

$$m = 1$$

Imaginary  $\Rightarrow$  Case III  
underdamping.

$$x = e^{-\alpha t} (c_1 \cos(\omega t) + c_2 \sin(\omega t))$$

$$x = e^{-2.5t} (c_1 \cos(1.98t) + c_2 \sin(1.98t))$$

$$x(0) = 2$$

$$x'(0) = -.5$$

$$x(0) = c_1 = 2$$

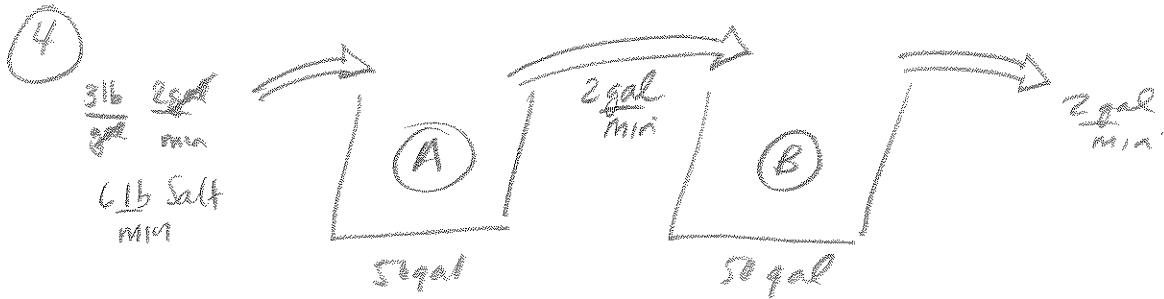
$$x'(0) = (-2.5e^{-2.5t})(c_1 \cos(1.98t)) + e^{-2.5t}(1.98)(c_1 \cos(1.98t))$$

\* Note: did not write down for terms,  $\sin(0) = 0$

$$x'(0) = -.5 = -.25(c_1) + 1.98(c_2)$$

$$c_2 = 0$$

$$\therefore y = e^{-2.5t} (2 \cos(1.98t))$$



$$A(t) = 10$$

$$B(t) = 20$$

$A(t)$  - amount of salt at  $t$  in tank A (lb)

$B(t)$  - amount of salt at  $t$  in tank B (lb)

$$\frac{dR}{dt} = \text{Rate in} - \text{Rate Out}$$

$$\frac{dA}{dt} = 6 - \frac{2}{50} A$$

$$\frac{dB}{dt} = \frac{2}{50} A - \frac{2}{50} B$$

In Matrix form

$$\begin{bmatrix} \frac{dA}{dt} \\ \frac{dB}{dt} \end{bmatrix} = \begin{bmatrix} -\frac{2}{50} & 0 \\ \frac{2}{50} & -\frac{2}{50} \end{bmatrix} \begin{bmatrix} A \\ B \end{bmatrix} + \begin{bmatrix} 6 \\ 0 \end{bmatrix}$$

$$\text{Let } X = \begin{bmatrix} A \\ B \end{bmatrix}$$

$$X' = \frac{1}{50} \begin{bmatrix} -2 & 0 \\ 2 & -2 \end{bmatrix} X + \begin{bmatrix} 6 \\ 0 \end{bmatrix}$$

ANS

## Question 1

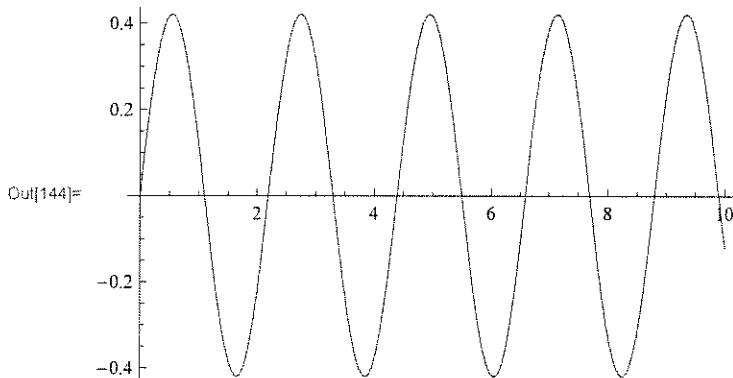
```
In[135]:= DSolve[{7 x''[t] + 57.14 x[t] == 0, x[0] == 0, x'[0] == 1.2}, x[t], t]
```

```
In[141]:= {{x[t] → 0.42001050039376636` Sin[2.8570714276785494` t]}}
q1[t_] = 0.42001050039376636` Sin[2.8570714276785494` t];
q1[5] // N
```

```
Out[141]:= {{x[t] → 0.420011 Sin[2.85707 t]}}
```

```
Out[143]:= 0.415407
```

```
In[144]:= Plot[q1[t], {t, 0, 10}]
```



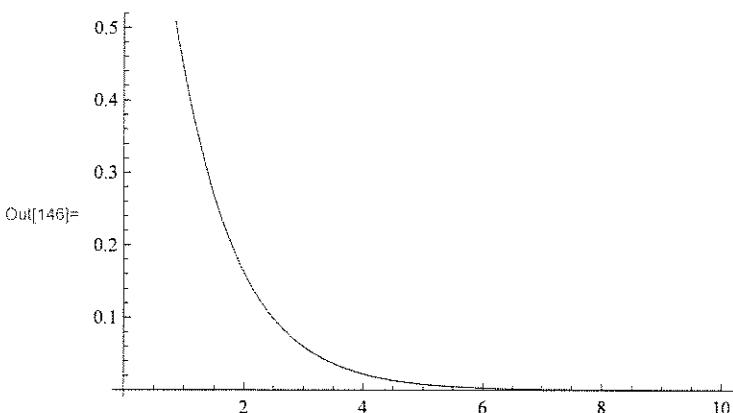
## Question 2

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In[140]:= DSolve[{2 x''[t] + 14 x'[t] + 12 x[t] == 0, x[0] == 1, x'[0] == 0}, x[t], t]
```

```
Out[140]:= {{x[t] → 1/5 e^-6 t (-1 + 6 e^5 t)}}
```

$$q2[t_] = \frac{1}{5} e^{-6t} (-1 + 6 e^{5t});$$

```
Plot[q2[t], {t, 0, 10}]
```



```
In[147]:= q2[5] // N
```

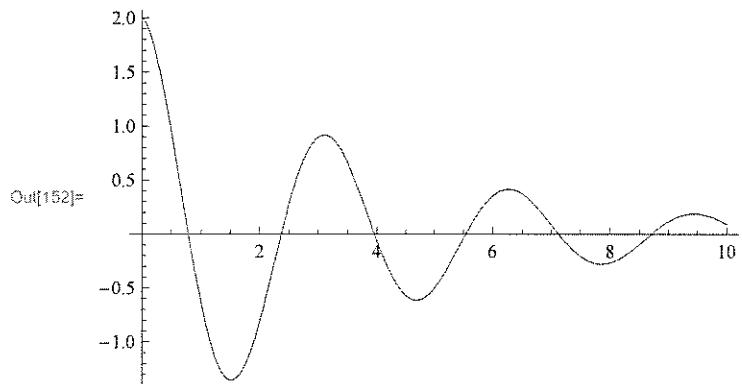
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Out[147]:= 0.00808554
```

## Question 3

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In[148]:= DSolve[{1 x''[t] + .5 x'[t] + 4 x[t] == 0, x[0] == 2, x'[0] == -.5}, x[t], t]
```

```
In[150]:= {{x[t] → 2. e^{-0.25 t} Cos[1.984313483298443` t]}}
q3[t_] = 2. e^{-0.25 t} Cos[1.984313483298443` t];
Plot[q3[t], {t, 0, 10}]
```

```
Out[150]= {{x[t] → 2. e^{-0.25 t} Cos[1.98431 t]}}
```



```
In[153]:= Solve[r^2 + .5 r + 4 == 0, r]
```

```
Out[153]= {{r → -0.25 - 1.98431 i}, {r → -0.25 + 1.98431 i}}
```



