

# MA205 Lesson 42

## Slope Fields

Thursday, November 1, 2007

# Outline

Admin

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Euler

# Admin

1. CPRC Cadets need to let me know who you are. Your makeup WPR III will be 28 November 2007 during normal class period.
2. Engineer Experience

# Admin

1. CPRC Cadets need to let me know who you are. Your makeup WPR III will be 28 November 2007 during normal class period.
2. Engineer Experience
3. Quiz - you will have 10 minutes

# Who's Birthday is it

Who's Birthday is it

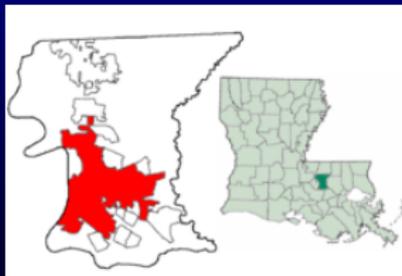
# Who's Birthday is it



# Who's Birthday is it



# Who's Birthday is it



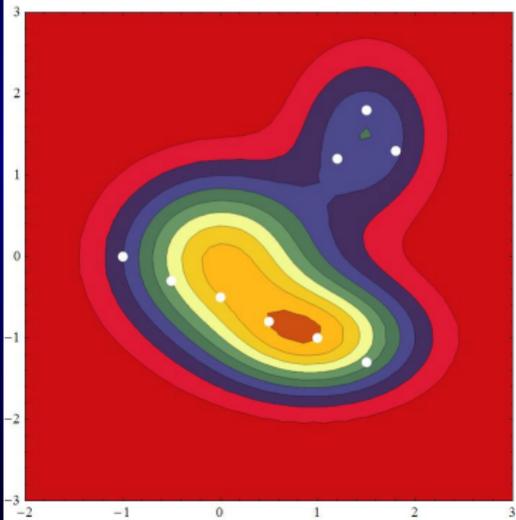
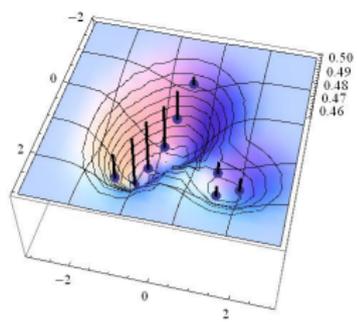
# Who's Birthday is it

Alicia Chan

# Solutions to Project

## Project

```
(* MA205 Project 2 Option A *)
<<Units`
TeT[x_, y_] :=
  0.5 - 0.04 (E-(x2+y2) + 0.5 E-(2(x-1.5)2+(y-1.5)2) + E-((x-1)2+2(y+1)2))
TeT[0, 0];
bouy3d = ListPointPlot3D[
  {{1.5, 1.8, TeT[1.5, 1.8] + .005}, {1.2, 1.2, TeT[1.2, 1.2] + .005},
   {1.8, 1.3, TeT[1.8, 1.3] + .005}, {-1, 0, TeT[-1, 0] + .005},
   {-0.5, -0.3, TeT[-0.5, -0.3] + .005}, {0, -0.5, TeT[0, -0.5] + .005},
   {0.5, -0.8, TeT[0.5, -0.8] + .005}, {1, -1, TeT[1, -1] + .005},
   {1.5, -1.3, TeT[1.5, -1.3] + .005}}, PlotStyle -> {PointSize[Large]},
  Filling -> 0.495, FillingStyle -> {Thick, Orange},
  PlotRange -> {{-2, 3}, {-3, 3}}];
lake3zmesh = Plot3D[TeT[x, y], {x, -2, 3}, {y, -3, 3},
  MeshFunctions -> {#3 &}, Mesh -> 10];
lake3 = Plot3D[TeT[x, y], {x, -2, 3}, {y, -3, 3}, Mesh -> 4];
Show[lake3, lake3zmesh, bouy3d]
lakec = ContourPlot[TeT[x, y], {x, -3, 3}, {y, -3, 3},
  Background -> None, PlotRange -> {{-2.0, 3}, {-3, 3}},
  ContourShading -> ColorData[35, "ColorList"]];
bouy = ListPlot[{{1.5, 1.8}, {1.2, 1.2}, {1.8, 1.3}, {-1, 0},
  {-0.5, -0.3}, {0, -0.5}, {0.5, -0.8}, {1, -1}, {1.5, -1.3}},
  PlotStyle -> {White, PointSize[Large]};
Show[{lakec, bouy}]
a = -2; b = 3; c = -3; d = 3;
DTeT[x_, y_] := If[TeT[x, y] ≤ 0.495, 0.495 - TeT[x, y], 0]
LakeV = NIntegrate[DTeT[x, y], {x, a, b}, {y, c, d}]
AveC = 3.57647626819842;
AveCC = Convert[AveC Micro Gram / Liter, MetricTon / Mile3]
f[V_, A_] := 0.38 * V-0.75 * A0.25
f[LakeV, AveCC]
```



0.174301

$$\frac{14.9074 \text{ MetricTon}}{\text{Mile}^3}$$

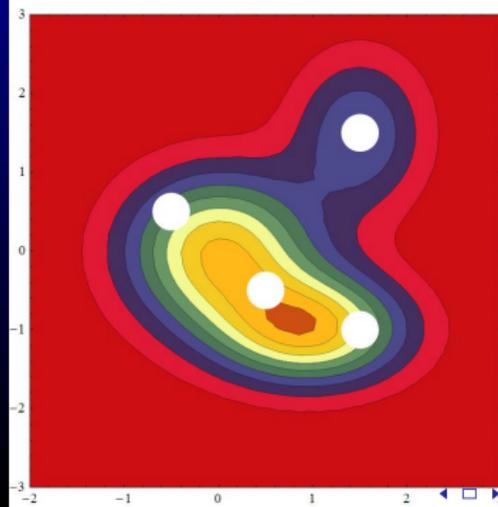
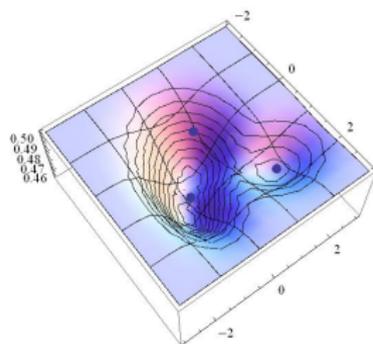
$$2.76796 \left( \frac{\text{MetricTon}}{\text{Mile}^3} \right)^{0.25}$$

```
(* Option B *)
TeTx[x_, y_] =  $\partial_x$  TeT[x, y];
TeTy[x_, y_] =  $\partial_y$  TeT[x, y];
LakeBed[x_, y_] =
  If[TeT[x, y] < 0.495,  $\sqrt{1 + (\text{TeTx}[x, y])^2 + (\text{TeTy}[x, y])^2}$ , 0];
LakeSA = NIntegrate[LakeBed[x, y], {x, -2, 3}, {y, -3, 3}]
RobotAve = 1.48585510802429;
RobotAveC = Convert[RobotAve Milli Gram / (Feet)2,
  Kilo Gram / Mile2]
Arsenic[SA_, Ava_] := 5.4 * SA-0.75 * Ava0.25;
Arsenic[LakeSA, RobotAveC]
Robot3d = ListPointPlot3D[
  {{1.5, 1.5, TeT[1.5, 1.5] + .005},
   {-0.5, 0.5, TeT[-0.5, 0.5] + .005},
   {0.5, -0.5, TeT[0.5, -0.5] + .005},
   {1.5, -1, TeT[1.5, -1] + .005}},
  PlotStyle → {PointSize[Large]},
  PlotRange → {{-2, 3}, {-3, 3}}];
Robot = ListPlot[{{1.5, 1.5}, {-0.5, 0.5}, {0.5, -0.5},
  {1.5, -1}}, PlotStyle → {White, PointSize[.08]};
Show[lake3, lake3zmesh, Robot3d]
Show[{lakec, Robot}]
```

12.6184

$$\frac{41.4233 \text{ Gram Kilo}}{\text{Mile}^2}$$

$$2.04622 \left( \frac{\text{Gram Kilo}}{\text{Mile}^2} \right)^{0.25}$$



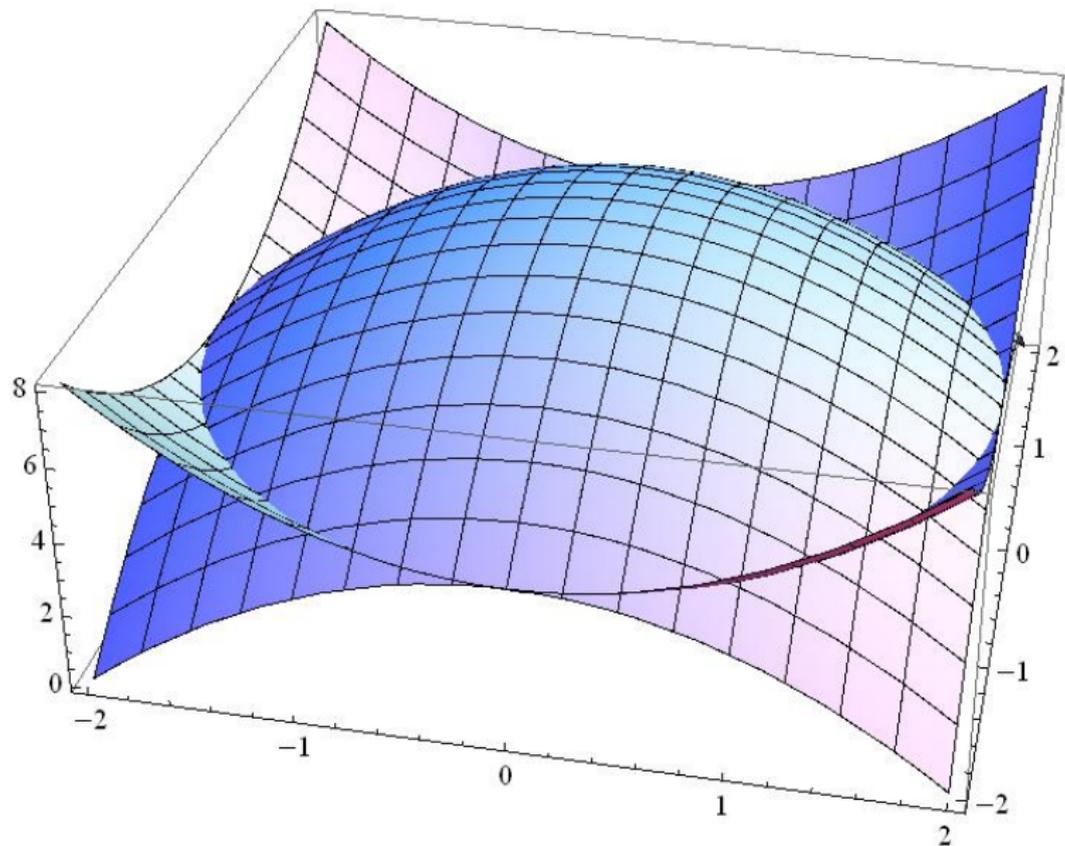
# Solutions to Homework

## Homework

```
yeast1[x_, y_] := 8 - x2 - y2
yeast2[x_, y_] := x2 + y2
yeast1p = Plot3D[yeast1[x, y], {x, -2, 2}, {y, -2, 2}];
yeast2p = Plot3D[yeast2[x, y], {x, -2, 2}, {y, -2, 2}];

$$\int_{-2}^2 \int_{-2}^2 (\text{yeast1}[x, y] - \text{yeast2}[x, y]) \, dy \, dx$$

Show[yeast2p, yeast1p]
```



```
yeastc[x_, y_] := 1 000 000 * (300 - 3 x^2 - 3 y^2)

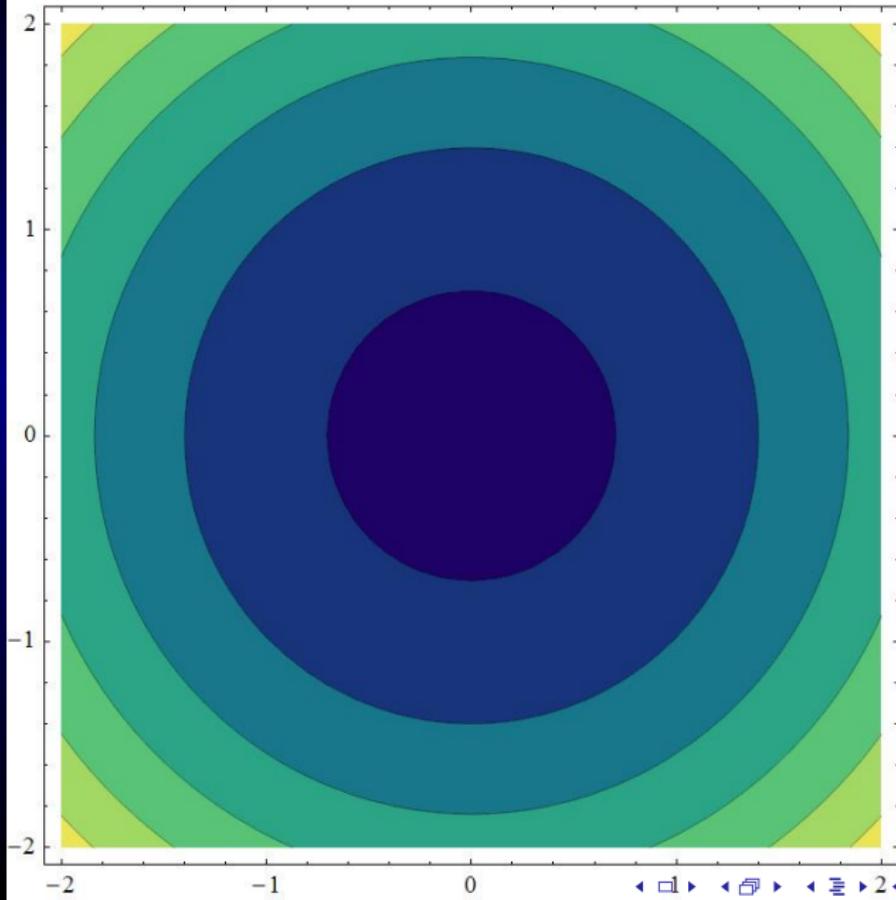
$$\int_{-2}^2 \int_{-2}^2 \text{yeastc}[x, y] \, dx \, dy$$


$$\frac{1}{16} \int_{-2}^2 \int_{-2}^2 \text{yeastc}[x, y] \, dx \, dy$$

ContourPlot[1 / yeastc[x, y], {x, -2, 2}, {y, -2, 2},
  Mesh → 10, ColorFunction → "BlueGreenYellow"]
```

4 672 000 000

292 000 000



```
yeastbsct[x_] := 2 -  $\frac{1}{2} x^2$ 
```

```
yeastbscb[x_] :=
```

```
Piecewise[{{-2 - x, -2 ≤ x < 0}, {x - 2, 0 ≤ x ≤ 2}},  
{x, -2, 2}];
```

```
ytbs = Plot[yeastbsct[x], {x, -2, 2}, PlotRange → -2];
```

```
ybbs = Plot[yeastbscb[x], {x, -2, 2}];
```

```
Show[ytbs, ybbs];
```

```
 $\int_{-2}^0 \int_{-2-x}^{2-\frac{1}{2}x^2}$  yeastc[x, y] dy dx +
```

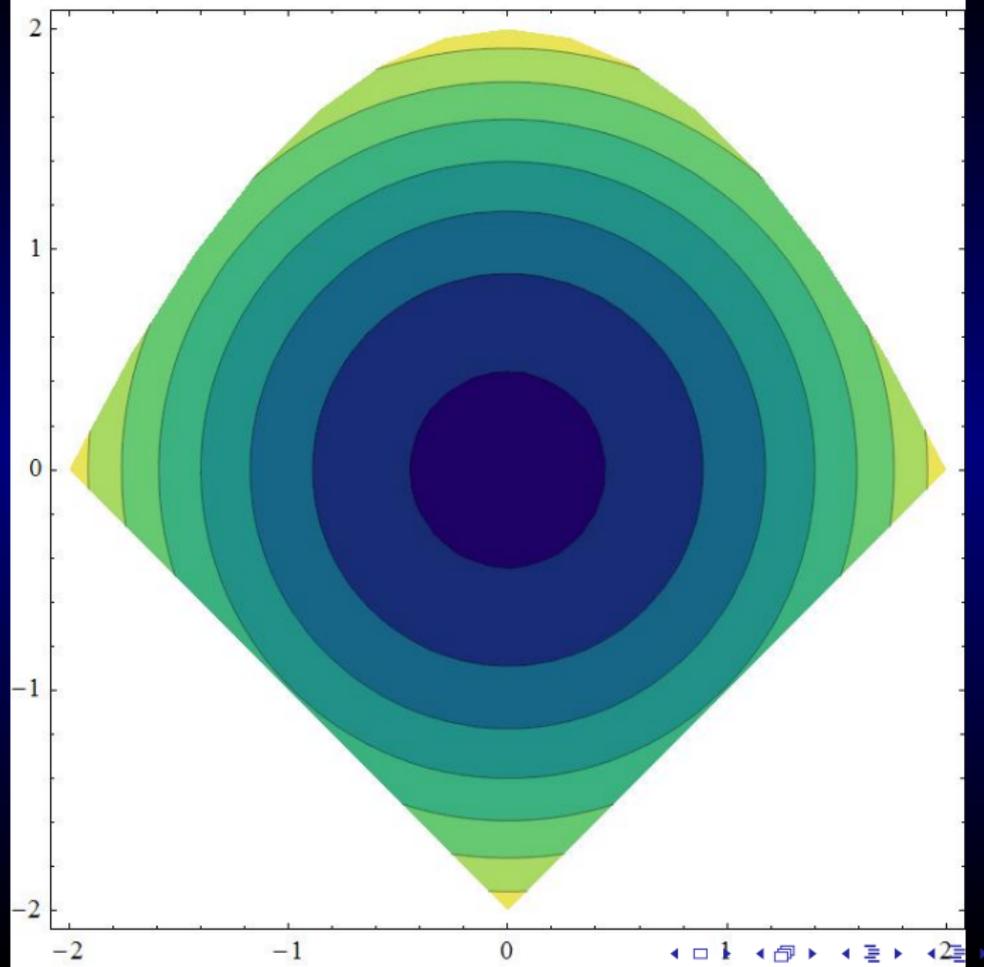
```
 $\int_0^2 \int_{-2+x}^{2-\frac{1}{2}x^2}$  yeastc[x, y] dy dx
```

```
ContourPlot[1/yeastc[x, y], {x, -2, 2},
```

```
{y, yeastbsct[x], yeastbscb[x]}, Mesh → 10,
```

```
ColorFunction → "BlueGreenYellow"]
```

$2.75657 \times 10^9$



```
yeastcc[x_, y_] := 10 000 000 * (300 - 5 x^2 - 5 y^2)
```

```
yeastccp[θ_, r_] := yeastcc[r * Cos[θ], r * Sin[θ]]
```

```

$$\int_0^{2\pi} \int_0^{5.25} \text{yeastcc}[r * \text{Cos}[\theta], r * \text{Sin}[\theta]] r dr d\theta$$

```

```

$$\int_{-5.25}^{5.25} \int_{-\sqrt{5.25^2 - x^2}}^{\sqrt{5.25^2 - x^2}} \text{yeastcc}[x, y] dy dx$$

```

```

$$\int_0^{2\pi} \int_0^{5.25} \text{yeastccp}[\theta, r] r dr d\theta$$

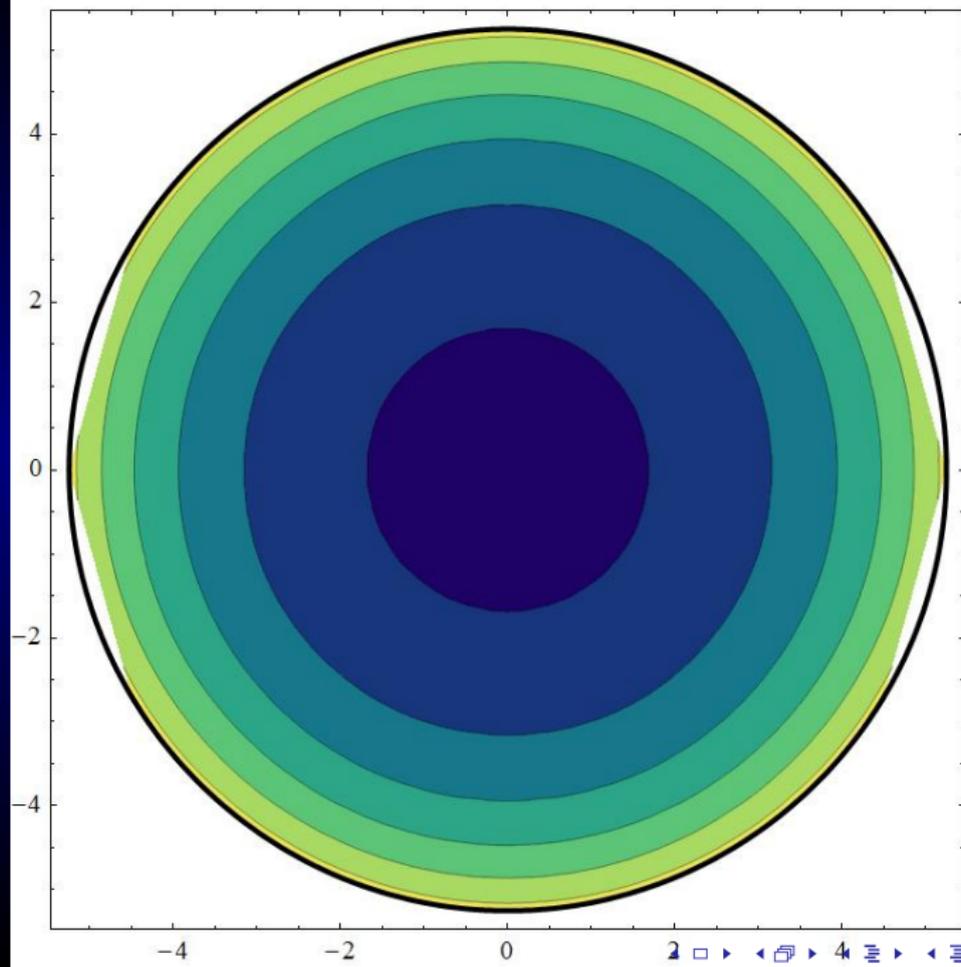
```

```
yeastccplot = ContourPlot[1 / yeastcc[x, y],  
  {x, -5.25, 5.25}, {y, - $\sqrt{5.25^2 - x^2}$ ,  $\sqrt{5.25^2 - x^2}$ },  
  Mesh → 10, ColorFunction → "BlueGreenYellow"];
```

```
carboy = PolarPlot[5.25, {θ, 0, 2 π},  
  PlotStyle → {Thick, Black}];
```

```
Show[yeastccplot, carboy]
```

$2.00104 \times 10^{11}$

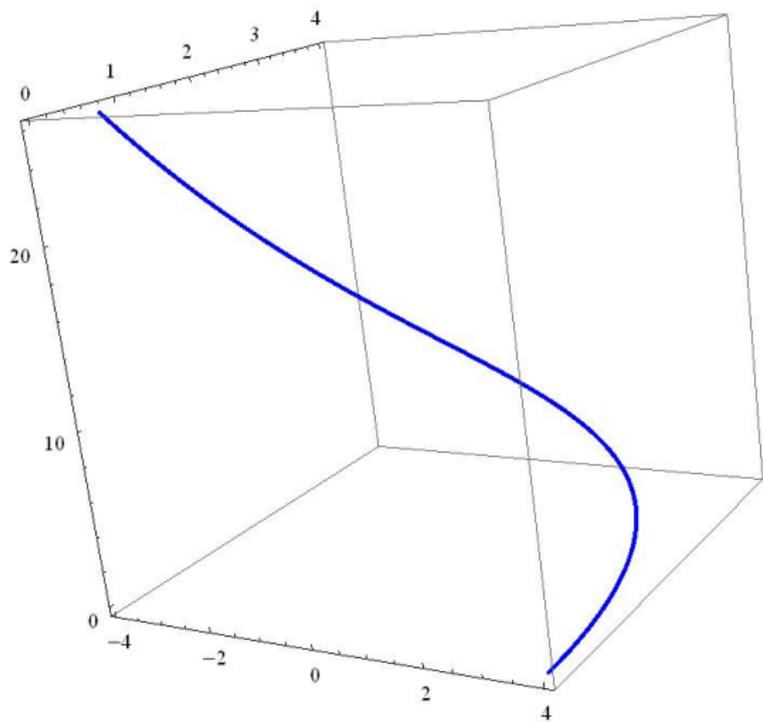


```

yeastbagx[t_] := 4 Cos[t]
yeastbagy[t_] := 4 Sin[t]
yeastbagz[t_] := t3
ParametricPlot3D[
  {yeastbagx[t], yeastbagy[t], yeastbagz[t]},
  {t, 0, 3√26}, BoxRatios → {1, 1, 1}, PlotPoints → 150,
  PlotRange → All, PlotStyle → {Thick, Blue}]
Solve[t3 == 26, t] // N
Animate[ParametricPlot3D[
  {yeastbagx[t], yeastbagy[t], yeastbagz[t]},
  {t, 0, z}, BoxRatios → {1, 1, 1}, PlotPoints → 150,
  PlotRange → {{-4, 4}, {-4, 4}, {0, 26}},
  PlotStyle → {Thick, Blue}], {z, 0, 3√26}]

```

Out[144]=



Out[145]=

$\{\{t \rightarrow -1.48125 - 2.5656 i\}, \{t \rightarrow 2.9625\}, \{t \rightarrow -1.48125 + 2.5656 i\}\}$

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# Course Guide

## Objectives

### Objectives

- ▶ Create a slope field for a given first order differential equation.
- ▶ Approximate a solution to a first order differential equation using a slope field.
- ▶ Discuss the long term behavior of a first order differential equation based on what the slope field looks like.

# Course Guide

## Readings

### Read

- ▶ Stewart, Chapter 9, section 2, pages 592-598.

# Course Guide

## Think About

- ▶ Why use a graphical solution instead of a computed function?
- ▶ Can a graphical solution tell you more than a function can tell you?

# Course Guide

## Mathematica Commands and Tasks You Need To Know

- ▶ Follow directions in the course guide to install DETools exactly. This should be done already.

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# Intro to Differential Equations

Questions?

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# Slope Fields

1. Start up Mathematica
2. We will test Mathematica with a few problems
3. We will use the formula  $y'(t) = y$  with initial conditions  $y(0) = 0, y(0) = 2, y(0) = 4$  that we will trace on our screens.
4. Then we can input those curves in Mathematica to see how close we are.

# More Slope Fields

1. Exponential Growth
2. Where  $\frac{dP}{dt} = kP, k > 0$
3. Put this in DEPlot

# Logistic Growth

1. Logistic Growth
2. Where  $\frac{dP}{dt} = r(M - P)P, r > 0$
3. Put this in DEPlot

# Test Problem

► Page 211 Course Guide

# Did you work with Thayer Last Night?

- ▶ Do Mechanics Based Problem 1
- ▶ Then we will try PSP 4

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# Euler

Euler approximations

# Questions